

8 axes high-speed line driver output motion control board for PCI(high-performance version)

## SMC-8DF-PCI



\* Specifications, color and design of the products are subject to change without notice.

This product is a PCI board that supports stepping motors and ("pulse string input" types of) servomotors. This product can perform motor control for up to 8 axes. Multi-axis independent control and linear/circular interpolation control are performed via a motor driver unit. It can store positioning information for up to 1024 frames per axis and control multiple axes simultaneously. In addition, it can override speed/target positions during operation. Windows driver is bundled with this product. These various functions make it possible to build complex positioning control systems for variety of uses such as manufacturing devices and test devices.

### About Migration From The Existing Products

This product cannot use [API-SMC(98/PC)] (Disk attached) which is the driver software for the existing products SMC-2P(PCI), SMC-4P(PCI), and SMC-3(PC). [API-SMC(98/PC)] (bundled Disk) cannot be used. Please use [API-SMC(WDM)] (bundled Disk) which is the driver software for this product. As a reference material when migrating from the existing products to this product, "Migration guide" which summarizes migration methods and differences about initial settings and API function units is provided. Please use the guide for your reference.

"Migration guide" can be downloaded from the download library of CONTEC's Web site (<http://www.contec.com/download>)

## Features

### Capable of multi-axis independent control and pulse output up to 6.5Mpps

Control for up to 8 axes and motor control pulse output up to 6.5Mpps are available.

Command pulse for motor control supports common pulse, independent pulse and 90° phase difference pulse.

Limit input 3channels/axis, general-purpose input 7channels/axis, and general-purpose output 3channels/axis are equipped. Also, depending on the software setting, 6 general-purpose inputs can be used as alarm inputs, and general-purpose outputs as deviation counter clear outputs.

### Capable of various control operations such as positioning, linear/circular interpolation, frame continuous operations, synchronization control, and so on

Various control operations such as positioning, origin returning, linear/circular interpolation, S-curve acceleration/deceleration, frame continuous motion, synchronization control, and so on are available. Changing speed/target position during operation is available.

"PCL6045 series" from Nippon Pulse Motor CO., LTD. is used as the motor control IC.

### Provided with various input/output formats enabling connection to an encoder input circuit as well as pulse output circuit.

Encoder input circuits can be connected with differential output, TTL level output, and open-collector output. Pulse output circuits can be connected with differential input, opto-coupler and TTL level input.

### Capable of storing positioning information up to 1024 frames for each axis and control without extra CPU load

The parameters which are necessary for motor operations such as travel distance, travel speed, acceleration/deceleration rate, and so on as 1 frame can be stored up to 1024 frames for each axis. In addition, the control from the ending of 1 frame to the beginning of the next frame is mainly performed by hardware, complex continuous positioning can operate at a high speed. It is possible to repeatedly execute the frame after executing a frame once (loop operation).

### With the multi-boards and axis synchronization control function, capable of aligning the timing for operation start and end

Synchronization control of multi-axis simultaneous start/stop control, linear interpolation operation is available.

Synchronization control of up to 16 boards (128 axes) is possible, when dedicated synchronization control cables are connected.

### Windows compatible driver libraries are attached.

Using the attached driver library API-PAC(W32) makes it possible to create applications of Windows. In addition, a diagnostic program by which the operations of hardware can be checked is provided.

### Connector shape and pin assignments are compatible with SMC-8DL-PCI

Since this product is compatible with SMC-8DL-PCI in the connector shape and signal allocation, it can be replaced with them.

### Provided with a terminal strip CCB-SMC2 (option) to which driver units up to 4 pieces can be connected

A dedicated terminal strip CCB-SMC2 (option) which assigns signals for each axis is provided. Driver units and limit sensors for stepping motors and servo motors can be connected up to 4 pieces.

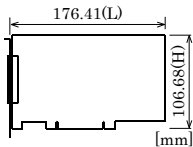
## Specification

### Common Section

Item	Specification
Control target	Stepping motor or servo motor driver unit (pulse train input type)
Number of axes to control	8 axes
Device used	PCL6045B (Nippon Pulse Motor CO., LTD.) or equivalence to it
Interrupt	1 ch
Interrupt factor	When stopping by positive-direction end limit input ON When stopping by negative-direction end limit input ON At the time of stop by alarm input on When stopping by simultaneous stop operation When stopping by deceleration (decelerated stop) input on When occurring the encoder input error The other event (setting by the software)
The number of sheets that can be used simultaneously	16 sheets
I/O address	Any 128 ports boundary
Current consumption (Max.)	5VDC 1600mA
Operating condition	0 - 50°C, 10 - 90% (No condensation)
PCI bus specification	32-bit, 33MHz, Universal key shapes supported *1
Dimension (mm)	176.41(L) x 106.68(H)
Connector used	HDRA-E100W1LFDT1EC-SL+ [mfd by HONDA TSUSHIN KOGYO CO., LTD.] or equivalence to it
Weight	150g
Certification	RoHS, CE, VCCI

\*1 This board requires power supply at +5V from an expansion slot (it does not work on a machine with a +3.3V power supply alone).

### Board Dimensions



The standard outside dimension (L) is the distance from the end of the board to the outer surface of the slot cover.

### Encoder Input Section

Item	Specification
Encode type	Incremental
Maximum counter value	8000000h - 7FFFFFFh(-134,217,728 - 134,217,727), 28 bit
Input signal type	Single-phase input (UP/DOWN/Z) / Phase input (A/B/Z)
Supported output type	Differential output, TTL level output, open-collector output
Device used	AM26LS32A(T.I.) or equivalence to it
Terminal resistor	150Ω (Separable with SW)
Receiver input sensitivity	±200mV
In-phase input voltage range	±7V
Distance in which signal can be extended	10m (Depending on the time of connecting the differential output, wiring environment and input frequency) 3m (Depending on the time of connecting the open-collector output, wiring environment and input frequency) 1.5m (Depending on the time of connecting the TTL level output, wiring environment and input frequency)
Response frequency (Max.)	5MHz duty (When connecting the differential output, 2-phase Input, Multiply by 4, duty 50%) 3MHz duty (When connecting the TTL level output, 2-phase Input, Multiply by 4, duty 50%) 1MHz duty (When connecting the open-collector output, 2-phase Input, Multiply by 4, duty 50%)

### Limit Input Section

Item	Specification
Signal channel	3channels/axis (original point, Forward limit, reserve limit)
Input signal name	ORG : origin input +LIM : positive direction end limit input -LIM : negative direction end limit input
Input logic	Enables selecting the positive/negative logic by using the Software
Input type	Opto-coupler input (corresponding to current sink output)
Response time (Max.)	200 μsec
Input resistor	4.7kΩ
Input ON current	2.0mA or more
Input OFF current	0.16mA or less
External circuit power supply	12V - 24VDC(±10%)

### General-purpose Input Section

Item	Specification
Signal channel	7channels/axis
Input signal name	IN1/ALM : alarm input, general-purpose input IN2/INP : positioning completion input, general-purpose input IN3/SD : deceleration (decelerated stop) input, general-purpose input IN4/LTC : counter latch input, general-purpose input IN5/PCS : positioning control start input, general-purpose input IN6/CLR : counter clear input, general-purpose input IN7 : general-purpose input
Input logic	Enables selecting the positive/negative logic by using the Software
Input type	Opto-coupler input (corresponding to current sink output)
Response time (Max.)	200 μsec
Input resistor	4.7kΩ
Input ON current	2.0mA or more
Input OFF current	0.16mA or less
External circuit power supply	12V - 24VDC(±10%)

### Pulse Output Section

Item	Specification
Pulse rate	0.1 - 6.5 Mpps
Output signal name	CW : pulse / CW output CCW : direction / CCW output
Output signal system	2 Pulse types (pulse for positive/negative direction) or the common pulse type (pulse signal/directional signal) 90°C phase difference pulse (lead/lag pulse)
Output form	Un-isolated differential line driver output
Device used	AM26LS31(T.I.) or equivalence to it
H level output voltage	2.5V - 5.25V
L level output voltage	0V - 0.5V
Rated output current (Max.)	20mA

### General-purpose Output Section

Item	Specification
Number of signal channel	3channels/axis
Output signal name	OUT1 : general-purpose output OUT2 : general-purpose output OUT3 : general-purpose output (Each output pin can be switched with the following functions) ALMCLR : alarm clear output ERC : driver differential clear output CP1 : comparator1 output CP2 : comparator2 output
Signal specification	Un-isolated open collector output (current sink type) (Enables selecting the positive/negative logic by using the Software)
Response time (Max.)	10μsec (when using the loading on the input side 510Ω, +24VDC)
Rated output current (Max.)	100mA per 1ch, 300mA per 1axis
Rated output withstanding voltage (Max.)	50VDC

## Support Software

### Windows version of motion control driver API-SMC(WDM) [Stored on the bundled Disk driver library API-PAC(W32)]

The API-SMC(WDM) is the Windows version driver library software that provides products in the form of Win32 API functions (DLL). Various sample programs such as Visual Basic and Visual C++, etc and diagnostic program useful for checking operation is provided.

You can download the updated version from the CONTEC's Web site (<http://www.contec.com/apipac/>). For more details on the supported OS, applicable language and new information, please visit the CONTEC's Web site.

## Cable & Connector

### Cable (Option)

Shielded Cable With Two 100pin Connector

- : PCB100PS-0.5 (0.5m)
- : PCB100PS-1.5 (1.5m)
- : PCB100PS-3 (3m)
- : PCB100PS-5 (5m)

Flat Cable with One 100-Pin Connector

- : PCA100P-1.5 (1.5m)
- : PCA100P-3 (3m)
- : PCA100P-5 (5m)

## Accessories

### Accessories (Option)

Connection Conversion Board for SMC : CCB-SMC2 \*1\*2\*3  
Screw Terminal (M3\*100) : EPD-100A \*2\*3\*4

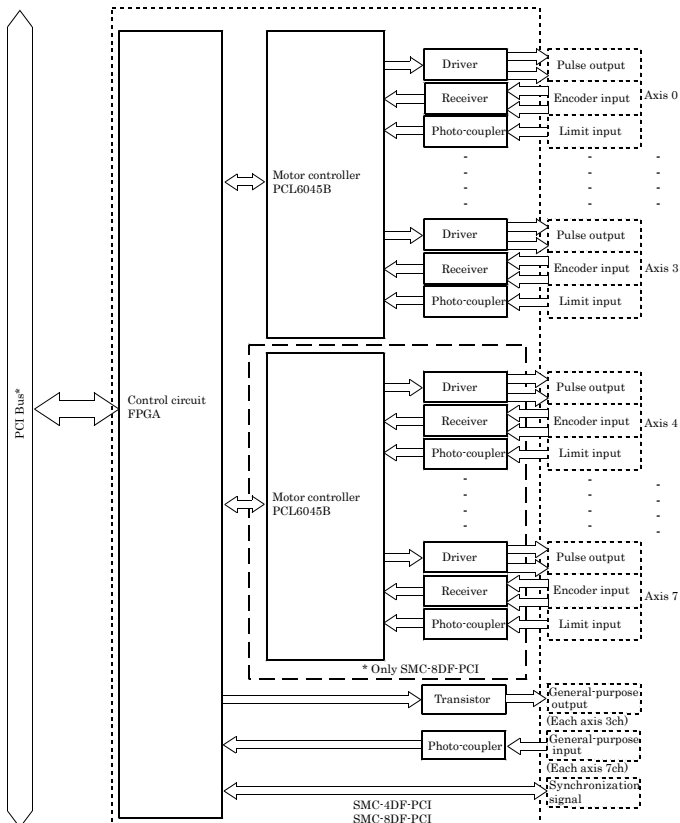
- \*1 Distributes 100-pin 0.8-mm pitch connector x 1 to: D-SUB 37 connector x 4, D-SUB-9 connector x 4.
- \*2 A PCB100PS optional cable is required separately.
- \*3 Cables and accessories are required each connector.
- \*4 "Spring-up" type terminal is used to prevent terminal screws from falling off.
- \* Check the CONTEC's Web site for more information on these options.

## Packing List

Board [SMC-8DF-PCI] ...1  
First step guide ...1  
Disk \*1 [API-PAC(W32)] ...1  
Synchronization control cable (10cm) ...1  
Serial number label...1  
Product Registration Card & Warranty Certificate ...1

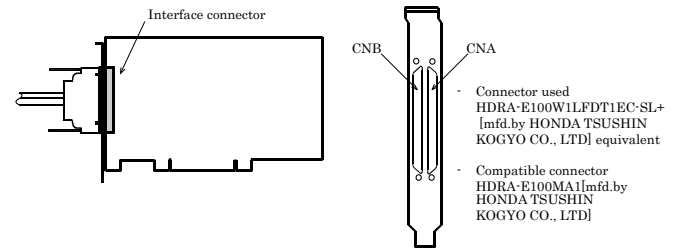
- \*1 The Disk contains the driver software and User's Guide.

## Block Diagram



## How to connect the connectors

The on-board interface connector (CNA, CNB) is used when connecting this product and the external devices.



- \* Please refer to this page for more information on the supported cable and accessories. Cables and accessories are required each connector.

## Pin Assignments of Interface Connector (CNA, CNB)

axis0	axis1	axis2	axis3
axis0 : P-COM	axis1 : IN1/ALM	axis2 : P-COM	axis3 : IN1/ALM
axis0 : IN1/ALM	axis1 : IN2/INP	axis2 : IN1/ALM	axis3 : IN2/INP
axis0 : IN2/INP	axis1 : IN3/SD	axis2 : IN2/INP	axis3 : IN3/SD
axis0 : IN3/SD	axis1 : IN4/LTC	axis2 : IN3/SD	axis3 : IN4/LTC
axis0 : IN4/LTC	axis1 : IN5/PCS	axis2 : IN4/LTC	axis3 : IN5/PCS
axis0 : IN5/PCS	axis1 : IN6/CLR	axis2 : IN5/PCS	axis3 : IN6/CLR
axis0 : IN6/CLR	axis1 : IN7	axis2 : IN6/CLR	axis3 : IN7
axis0 : IN7	axis1 : ORG	axis2 : IN7	axis3 : ORG
axis0 : ORG	axis1 : +LIM	axis2 : ORG	axis3 : +LIM
axis0 : +LIM	axis1 : -LIM	axis2 : +LIM	axis3 : -LIM
axis0 : -LIM	axis1 : P-COM	axis2 : -LIM	axis3 : P-COM
axis1 : P-COM	axis1 : IN1/ALM	axis3 : P-COM	axis3 : IN1/ALM
axis1 : IN1/ALM	axis1 : IN2/INP	axis3 : IN1/ALM	axis3 : IN2/INP
axis1 : IN2/INP	axis1 : IN3/SD	axis3 : IN2/INP	axis3 : IN3/SD
axis1 : IN3/SD	axis1 : IN4/LTC	axis3 : IN3/SD	axis3 : IN4/LTC
axis1 : IN4/LTC	axis1 : IN5/PCS	axis3 : IN4/LTC	axis3 : IN5/PCS
axis1 : IN5/PCS	axis1 : IN6/CLR	axis3 : IN5/PCS	axis3 : IN6/CLR
axis1 : IN6/CLR	axis1 : IN7	axis3 : IN6/CLR	axis3 : IN7
axis1 : IN7	axis1 : ORG	axis3 : IN7	axis3 : ORG
axis1 : ORG	axis1 : +LIM	axis3 : ORG	axis3 : +LIM
axis1 : +LIM	axis1 : -LIM	axis3 : +LIM	axis3 : -LIM
axis1 : -LIM	axis1 : A+	axis3 : -LIM	axis3 : A+
axis1 : A+	axis1 : A-	axis3 : A+	axis3 : A-
axis1 : A-	axis1 : B+	axis3 : A-	axis3 : B+
axis1 : B+	axis1 : B-	axis3 : B+	axis3 : B-
axis1 : B-	axis1 : Z+	axis3 : B-	axis3 : Z+
axis1 : Z+	axis1 : Z-	axis3 : Z+	axis3 : Z-
axis1 : Z-	axis1 : A+	axis3 : Z-	axis3 : A+
axis1 : A+	axis1 : A-	axis3 : A+	axis3 : A-
axis1 : A-	axis1 : B+	axis3 : A-	axis3 : B+
axis1 : B+	axis1 : B-	axis3 : B+	axis3 : B-
axis1 : B-	axis1 : Z+	axis3 : B-	axis3 : Z+
axis1 : Z+	axis1 : Z-	axis3 : Z+	axis3 : Z-
axis1 : Z-	axis1 : OUT3	axis3 : Z-	axis3 : OUT3
axis1 : OUT3	axis1 : OUT2	axis3 : OUT3	axis3 : OUT2
axis1 : OUT2	axis1 : OUT1	axis3 : OUT2	axis3 : OUT1
axis1 : OUT1	axis1 : DIR+/CCW+	axis3 : OUT1	axis3 : DIR+/CCW+
axis1 : DIR+/CCW+	axis1 : DIR-/CCW-	axis3 : DIR+/CCW+	axis3 : DIR-/CCW-
axis1 : DIR-/CCW-	axis1 : OUT+/CW+	axis3 : DIR-/CCW-	axis3 : OUT+/CW+
axis1 : OUT+/CW+	axis1 : OUT-/CW-	axis3 : OUT+/CW+	axis3 : OUT-/CW-
axis1 : OUT-/CW-	axis1 : GND	axis3 : OUT-/CW-	axis3 : GND
axis1 : GND	axis1 : OUT3	axis3 : GND	axis3 : OUT3
axis1 : OUT3	axis1 : OUT2	axis3 : OUT3	axis3 : OUT2
axis1 : OUT2	axis1 : OUT1	axis3 : OUT2	axis3 : OUT1
axis1 : OUT1	axis1 : DIR+/CCW+	axis3 : OUT1	axis3 : DIR+/CCW+
axis1 : DIR+/CCW+	axis1 : DIR-/CCW-	axis3 : DIR+/CCW+	axis3 : DIR-/CCW-
axis1 : DIR-/CCW-	axis1 : OUT+/CW+	axis3 : DIR-/CCW-	axis3 : OUT+/CW+
axis1 : OUT+/CW+	axis1 : OUT-/CW-	axis3 : OUT+/CW+	axis3 : OUT-/CW-
axis1 : OUT-/CW-	axis1 : GND	axis3 : OUT-/CW-	axis3 : GND
axis1 : GND	axis1 : GND	axis3 : GND	axis3 : GND

- \* Axis0 - Axis3 of this manual corresponds to Axis No.1 - Axis No.4 in API-SMC(WDM).

P-COM	Plus common	B+	Encoder phase B input+
IN1/ALM	General-purpose input1/Alarm input	B-	Encoder phase B input-
IN2/INP	General-purpose input2/Positioning input	Z+	Encoder phase Z input+
IN3/SD	General-purpose input3/Slow down input	Z-	Encoder phase Z input-
IN4/LTC	General-purpose input4/counter latch input	OUT1	General-purpose output1
IN5/PCS	General-purpose input5/positioning operation start input	OUT2	General-purpose output2
IN6/CLR	General-purpose input6/Counter clear input	OUT3	General-purpose output3
IN7	General-purpose input7	DIR+/CCW+	Direction/CCW output+
ORG	Origin input	DIR-/CCW-	Direction/CCW output-
+LIM	Positive-direction limit	OUT+/CW+	Pulse/CW output+
-LIM	Negative-direction limit	OUT-/CW-	Pulse/CW output-
A+	Encoder phase A input+	GND	Power ground input (common to internal GND)
A-	Encoder phase A input-		

CNA	
GND-1	51-GND
axis7 : OUT-/CW-2	52-axis5 : OUT-/CW-
axis7 : OUT+/CW+3	53-axis5 : OUT+/CW+
axis7 : DIR-/CCW-4	54-axis5 : DIR-/CCW-
axis7 : DIR+/CCW+5	55-axis5 : DIR+/CCW+
axis7 : OUT1-6	56-axis5 : OUT1
axis7 : OUT2-7	57-axis5 : OUT2
axis7 : OUT3-8	58-axis5 : OUT3
GND-9	59-GND
axis6 : OUT-/CW-10	60-axis4 : OUT-/CW-
axis6 : OUT+/CW+11	61-axis4 : OUT+/CW+
axis6 : DIR-/CCW-12	62-axis4 : DIR-/CCW-
axis6 : DIR+/CCW+13	63-axis4 : DIR+/CCW+
axis6 : OUT1-14	64-axis4 : OUT1
axis6 : OUT2-15	65-axis4 : OUT2
axis6 : OUT3-16	66-axis4 : OUT3
axis7 : Z-17	67-axis5 : Z-
axis7 : Z+18	68-axis5 : Z+
axis7 : B-19	69-axis5 : B-
axis7 : B+20	70-axis5 : B+
axis7 : A-21	71-axis5 : A-
axis7 : A+22	72-axis5 : A+
axis6 : Z-23	73-axis4 : Z-
axis6 : Z+24	74-axis4 : Z+
axis6 : B-25	75-axis4 : B-
axis6 : B+26	76-axis4 : B+
axis6 : A-27	77-axis4 : A-
axis6 : A+28	78-axis4 : A+
axis7 : -LIM-29	79-axis5 : -LIM
axis7 : +LIM-30	80-axis5 : +LIM
axis7 : ORG-31	81-axis5 : ORG
axis7 : IN7-32	82-axis5 : IN7
axis7 : IN6/CLR-33	83-axis5 : IN6/CLR
axis7 : IN5/PCS-34	84-axis5 : IN5/PCS
axis7 : IN4/LTC-35	85-axis5 : IN4/LTC
axis7 : IN3/SD-36	86-axis5 : IN3/SD
axis7 : IN2/INP-37	87-axis5 : IN2/INP
axis7 : IN1/ALM-38	88-axis5 : IN1/ALM
axis7 : P-COM-39	89-axis5 : P-COM
axis6 : -LIM-40	90-axis4 : -LIM
axis6 : +LIM-41	91-axis4 : +LIM
axis6 : ORG-42	92-axis4 : ORG
axis6 : IN7-43	93-axis4 : IN7
axis6 : IN6/CLR-44	94-axis4 : IN6/CLR
axis6 : IN5/PCS-45	95-axis4 : IN5/PCS
axis6 : IN4/LTC-46	96-axis4 : IN4/LTC
axis6 : IN3/SD-47	97-axis4 : IN3/SD
axis6 : IN2/INP-48	98-axis4 : IN2/INP
axis6 : IN1/ALM-49	99-axis4 : IN1/ALM
axis6 : P-COM-50	100-axis4 : P-COM

\* Axis4 - Axis7 of this manual corresponds to Axis No.5 - Axis No.8 in API-SMC(WDM).

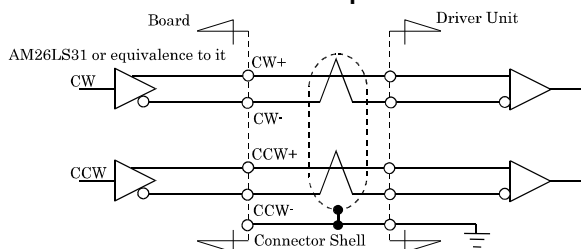
P-COM	Plus common	B+	Encoder phase B input+
IN1/ALM	General-purpose input1/Alarm input	B-	Encoder phase B input-
IN2/INP	General-purpose input2/Positioning input	Z+	Encoder phase Z input+
IN3/SD	General-purpose input3/Slow down input	Z-	Encoder phase Z input-
IN4/LTC	General-purpose input4/counter latch input	OUT1	General-purpose output1
IN5/PCS	General-purpose input5/positioning operation start input	OUT2	General-purpose output2
IN6/CLR	General-purpose input6/Counter clear input	OUT3	General-purpose output3
IN7	General-purpose input7	DIR+/CCW+	Direction/CCW output+
ORG	Origin input	DIR-/CCW-	Direction/CCW output-
+LIM	Positive-direction limit	OUT+/CW+	Pulse/CW output+
-LIM	Negative-direction limit	OUT-/CW-	Pulse/CW output-
A+	Encoder phase A input+	GND	Power ground input (common to internal GND)
A-	Encoder phase A input-		

## Connecting Output Signals

### Pulse output circuit (CW, CCW)

The pulse output circuit on this product, which is in the form of a differential line driver (AM26LS31 equivalent) as shown in the following figure, can be connected with differential input, opto-coupler, and TTL level input.

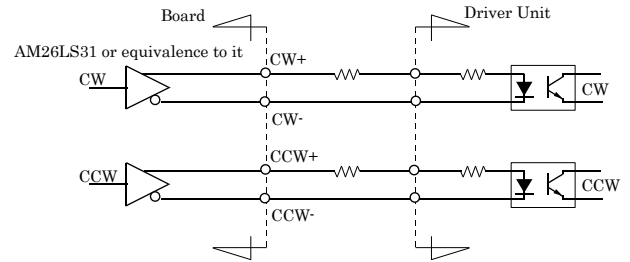
#### Connection with the differential input



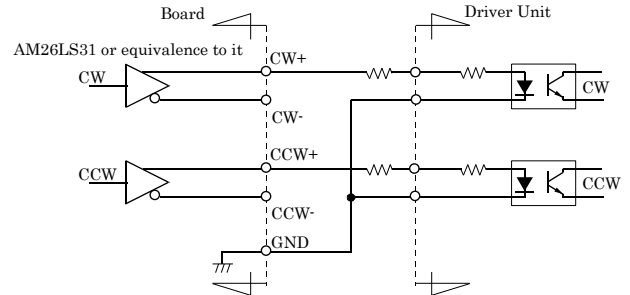
#### CAUTION

Please use the twisted-pair cable that does the shield processing as a noise measures when connecting it with the differential input.

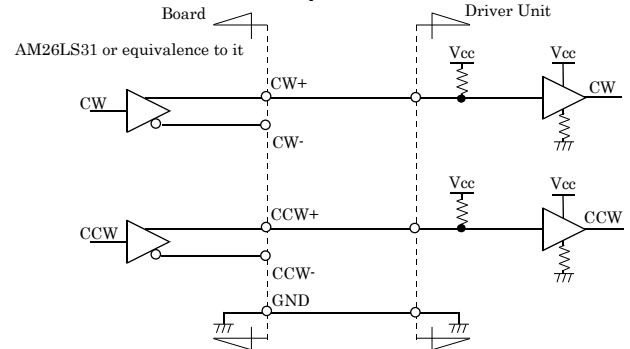
#### Connection with the opto-coupler input (When the driver unit guarantees the connection with the differential output)



#### Connection with the opto-coupler input



#### Connection with TTL level input



#### CAUTION

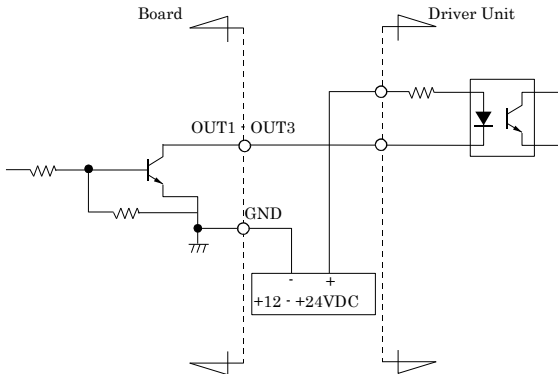
The pulse output part of this product outputs the voltage by 2.5V or more at the High level output, and outputs the voltage of 0.5V or less at the Low level output. When connecting with the photo-coupler input or the TTL level input, please connect it after confirming the specification in the pulse input part of the driver unit operates by the above-mentioned voltage.

In addition, please insert a current-limiting resistor according to the allowable current and drive current of the connected input circuit.

To prevent the circuit from malfunctioning due to noise, wire it as far away from other signal lines and noise sources as possible.

## Control signal/general-purpose signal output circuit (OUT1 - OUT3, ERC, CP1, CP2)

Output circuit of each output signal on this product is illustrated below. The signal output is an open-collector output. A ground wire must therefore be connected for driving.

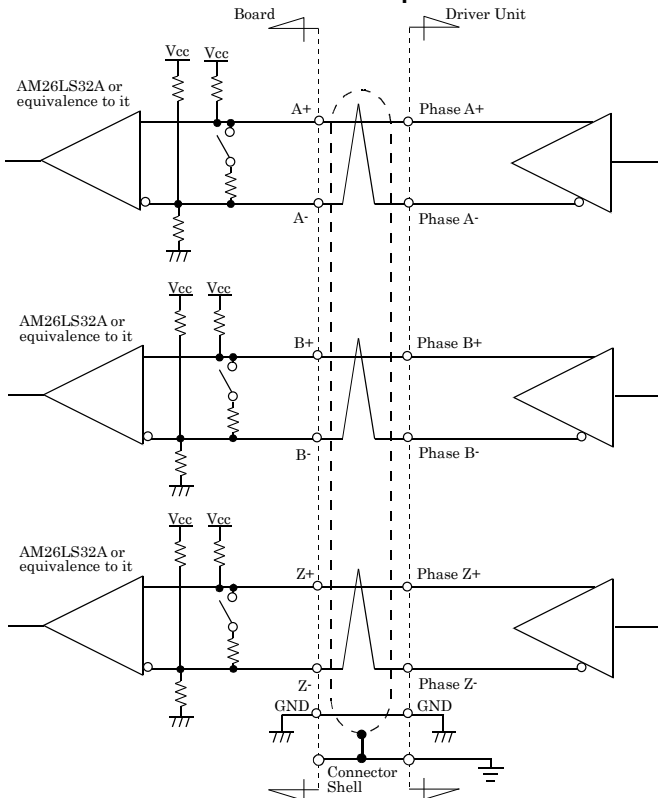


## Connecting Input Signals

### Encoder input circuit

Encoder input circuit on this product is illustrated below. The signal input is a differential input capable of connecting a line driver output, TTL level output and open-collector output.

### Connection with the differential output

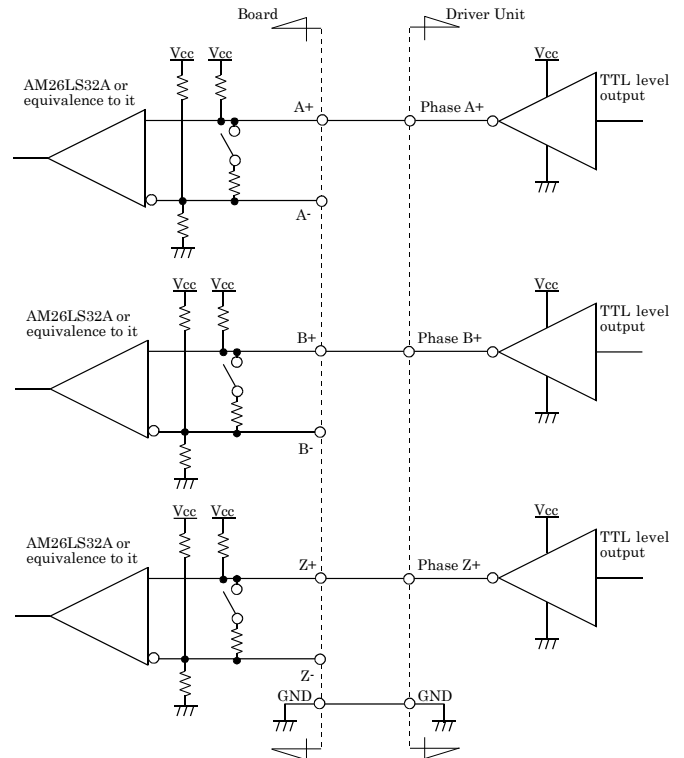


### CAUTION

Please use the twisted-pair cable that does the shield processing as a noise measures when connecting it with the differential output.

Restrict the use of cables to 10m for the line driver output.

### Connection with the TTL level output



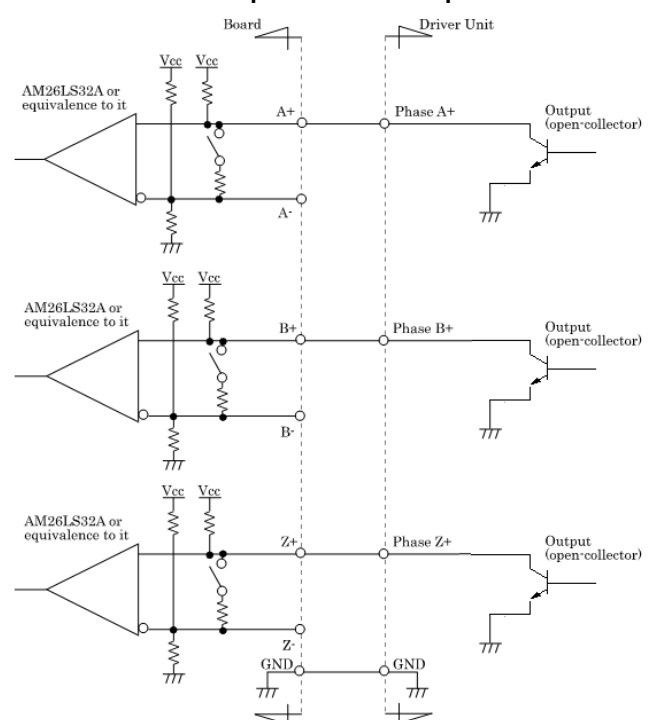
### CAUTION

When connecting TTL level output signals, please do not insert a terminating resistor with reference to "Setting the Terminating Resistor in chapter 2". When inserted with a terminating resistor (factory setting), this product may malfunction, overheat, or causes a failure.

Restrict the use of cables to 10m for the line driver output, 3m for the open-collector output, and 1.5m for the TTL level output.

To prevent the circuit from malfunctioning due to noise, wire it as far away from other signal lines and noise sources as possible.

### Connection with the open-collector output





### ⚠ CAUTION

When connecting open-collector output signals, please do not insert a terminating resistor with reference to "Setting the Terminating Resistor in chapter 2". When inserted with a terminating resistor (factory setting), this product may malfunction, overheat, or causes a failure.

Restrict the use of cables to 3m for the open-collector output.

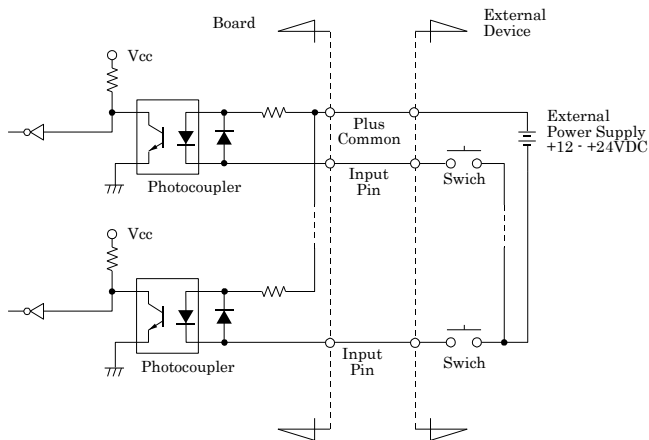
To prevent the circuit from malfunctioning due to noise, wire it as far away from other signal lines and noise sources as possible.

### Limit input/general-purpose input/control input circuit (IN1 - IN7, +LIM, -LIM, ORG)

The limit input/general-purpose input/control input circuit on this board is illustrated below.

The signal input is a current drive input by opto-coupler (Corresponding to the current sink output).

To drive the limit input/general-purpose input/control input block, therefore, an external power supply is required at +12 - +24 V.

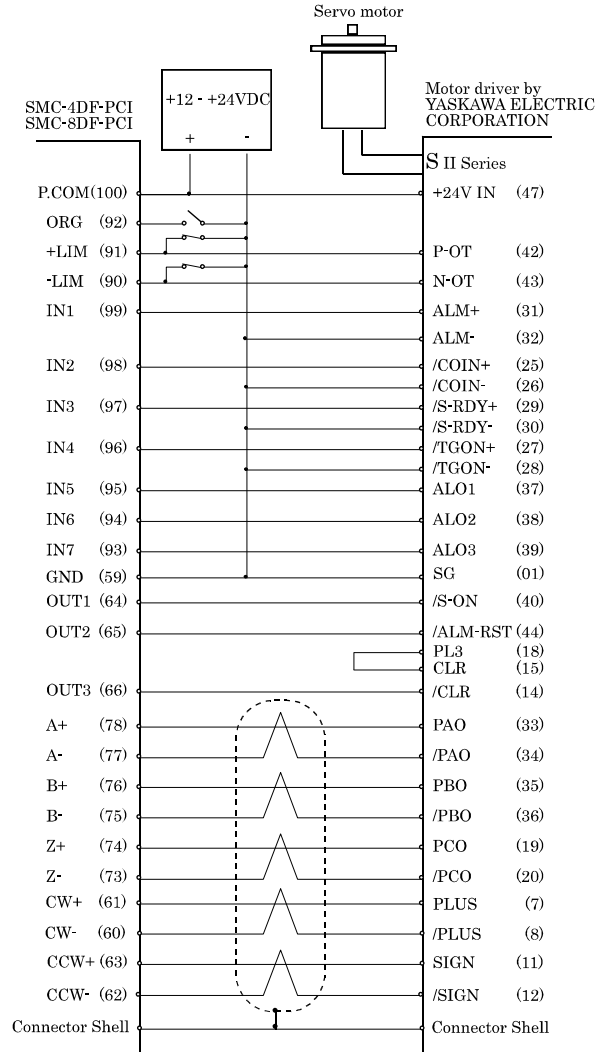


\* Input pin is IN1 - IN7, +LIM, -LIM, ORG.

## Connection Examples

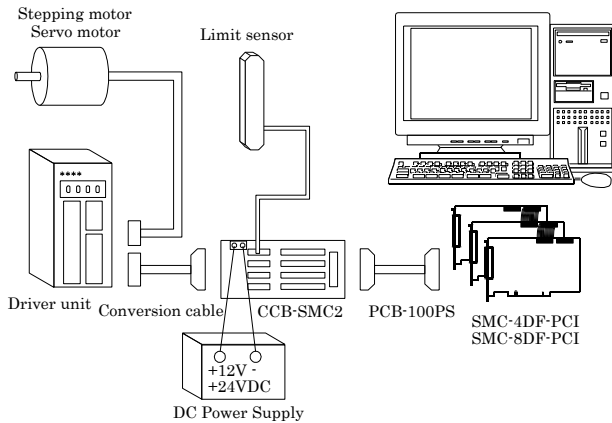
Given below are practical examples of connection of this product that outputs pulses by the independent pulsing method to motor drivers. These examples show the connections through axis0 (Axis No.1 in API-SMC(WDM)).

### Example of Connection to driver unit (Σ II Series) for Servo motor



\* Please connect the Shield Line of cable with the Connector Shell.

## Motion control system configuration



### Component features

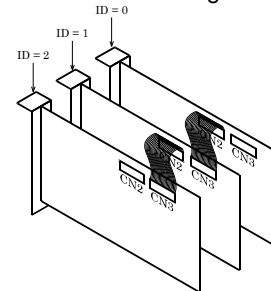
Item	Description
SMC-8DF-PCI (Main board)	When installed on the PC, this board generates pulses required for position control.
PCB-100PS (Option)	This cable connects the board to the CCB-SMC2.
CCB-SMC2 (Option)	This screw terminal is used to efficiently connect the devices (the board, driver unit, DC power supply, limit sensor) required for position control. The screw terminal can connect a four-axes motion control system alone.
Conversion cable (User)	The shape of the control connector of each driver unit is largely different depending on the manufacturer and type. A conversion cable must be prepared to connect each driver unit to the CCB-SMC2.
Driver unit (Motor maker)	Motor and driver unit to be subject to motion control.
Stepping motor/Servo motor (Motor maker)	Available in various types by motor capacity, power-supply voltage, and motor shape. Select the ones that best fit your needs.
Limit sensor (Switch maker)	This sensor is installed at the forward/backward limit and origin detection positions. When a table is used in the system, the sensor is bundled with the table. For a self-made system, use commercially available switches.
DC Power supply (Power supply maker)	Power supply to the CCB-SMC2. Use a 12 - 24-VDC power supply.

## Connecting the synchronization control connectors

There are synchronization signal control connectors (CN2, CN3) which enable synchronization operations of multiple pieces of this product. These connectors are used for connecting synchronization signal cables.

### Connection method

For synchronous operations of two or more boards, connect them with synchronization signal cables. Use a synchronization signal cable to connect the CN2 of a smaller ID board to the CN3 of the board with a greater board ID number.



### Configuration examples for synchronization operations (for SMC-8DF-PCI)

Cable connection	Unconnection	Connection	Connection	Unconnection
Synchronization connector number	CN3	CN2	CN3	CN2
Board ID number	First piece (ID = 0)	Second piece (ID = 1)	Third piece (ID = 2)	
Axis number	Axis 0 1 2 3 4 5 6 7	Axis 0 1 2 3 4 5 6 7	Axis 0 1 2 3 4 5 6 7	Axis 0 1 2 3 4 5 6 7
Configuration example 1	Group A (24-axes synchronization operations)			
Configuration example 2	Group A (12-axes synchronization operations)		Group B (12-axes synchronization operations)	
Configuration example 3	Group A (20-axes synchronization operations)			Group B (4-axes synchronization operations)

< Description for the above figure >

Configuration example 1:

when all axes (24 axes) working synchronously by using 3 pieces of SMC-8DF-PCI

Configuration example 2:

When divided into 2 groups of 12-axis synchronization operations by using 3 pieces of SMC-8DF-PCI

Configuration example 3:

When divided into 1 group of 20-axis synchronization operations and a group of 4-axis synchronization operations by using 3 pieces of SMC-8DF-PCI

### ⚠ CAUTION

Connectors for synchronization signals control of this product (CN2, CN3) are dedicated for SMC-4DF-PCI, SMC-8DF-PCI. Please do not connect this synchronization cable with products other than SMC-4DF-PCI and SMC-8DF-PCI.

Please make up synchronization groups from axis 0 (Axis No.1 or No. 4 in API-SMC(WDM) (Axis No.5 in API-SMC(WDM))).